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I of us are familiar with a thermodynamic

system, e.g. ideal gas. State variables, such as temperature, pressure, density, completely characterize a thermodynamic system and the laws of thermodynamics, relating the thermodynamic variables, can predict, to a limited extent, the future of a thermodynamic system. Likewise, laws of mechanics can explain the motion of Earth around the Sun or the motion of a car on a road. Similar laws of other branches of physics, such as quantum mechanics or hydrodynamics, can describe respective systems, to a certain extent. Many of us are fascinated by a dancing flock of birds on a nice evening just after the sunset or a beautiful collective motion of a fish school in the ocean (see Figure-1). Are there any laws that govern the motion of these systems of biological origin? Can we predict the future of such systems? Can we define thermodynamic-like variables that obey thermodynamic-like equations of state? Tremendous effort has been put in the past two decades to understand some of these questions.

Active or self-propelled systems [2,3] are the ones where each entity in the system can be thought of as a self-propelled particle i.e. they propel themselves using an internal source of energy or using energy from an external source but energy injection and dissipation happens at the individual particle level. Apart from the above mentioned two. there are numerous examples of active systems shown in Figure-1 over a vast range of scales. like microtubule propelled by motor proteins inside a cell, a group of single cell bacteria and even herds of animals, and human crowds belong to this class of non-equilibrium system. Moreover, there has

been a great effort in recent past to produce artificial selfpropelled particles from nanoscales to microscales to macroscales (see Figure-2) [4,5,6]. Apart from understanding some of the funda-

mental questions of non-equilibrium statistical physics, studying active systems could find potential applications in disease detection to targeted drug delivery [5], security, and environmental applications [6], to name a few.

Researchers have been trying to understand active systems performing experimental, numerical, and theoretical studies. Experimental studies over the vast range of scales have been shown to possess various dynamic states [7], phase transition between these states, crystallization and jamming [8], turbulent behavior [9], giant number fluctuations,

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Understanding a Collection of Selfpropelling Particles or An Active System **Using Computer Simulations!**

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Figure 1: (Top left) A flock of birds (Top right) Collective motion of school of fish (Bottom left) Experimental image of a bacterial colony (Bottom right) Cartoon diagram of microtubules bound with motor proteins[1].



Figure 2: Janus or two faced self-propelled particle possesses different properties due to different materials present on the two opposite faces. Hence, each half of the particle respond in a different way in an external driving field or in a background solvent. As a result rotational symmetry breaks and the particle propel in a preferred direction until rotational diffusion changes the direction of propulsion. Persistent Brownian motion in a dilute limit. (Top): Cartoon of isotropic Janus particles. (Bottom): Cartoon of anisotropic or rod like Janus particle with gold and platinum coating in two halves.

motility induced phase separation [10], thermodynamic-like properties, etc. But there are clear differences between these non-equilibrium properties and their passive counterparts (in few cases when they exist). Various simple models [2,11,9] have been proposed for active systems. To understand some of the properties of active systems, our group has been working on simple numerical models of microscale active systems. Microscale active particles are also known as micromotors or microswimmers [6]. They are, generally, immersed in a background solvent, e.g. water. Typical velocities of the microswimmers are tens of micrometers per second. Hence, Revnolds number of a system of microswimmers turns out to be very low (Re \sim 10 $^{-4}$ — 10 $^{-5}$). Consequently, inertial forces or the effective accelerations can be neglected in comparison to other forces, and the microswimmers acquire a constant propulsion speed; an over-damped system. Now, there are several mechanisms through which the propulsion speed of the microswimmers can be increased by a few orders of magnitude [12,13]. If we immerse those highly

"In near future, we hope to perform new studies that will eventually lead to general theories or laws in this domain of interdisciplinary science"

orders of magnitude higher than that of over-damped systems. Such highly motile self-propelled particles in a low viscous solvent are also known as microflyers[12]. We can not neglect the inertial contributions of microflyers. Recently, we have performed [14] numerical simulations of an agent-based model of microflyers. Our simulation techniques are similar to the Brownian dynamics simulation with some minor changes due to the active nature of the particles. For this purpose, we have upgraded the molecular dynamics code (MPMD[15]) to a multi-GPU code, which can run on modern hybrid CPU-GPU cluster (like ANTYA at

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IPR). Surprisingly enough, our study demonstrates that despite its non-equilibrium nature, the system of microflyers is found to observe equilibrium like Gaussian velocity distributions. We have extracted the equilibrium-like temperature of an inherent nonequilibrium system. With the accessibility of bigger and powerful computing facilities, many unknown areas that can be studied now which are difficult to study experimentally or analytically.

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